

### WORKSHOP BLOCK 1

CST/UTC+08 (Sunday 09/20)	EEST/UTC+03 (Sunday 09/20)	CEST/UTC+02 (Sunday 09/20)	EST/UTC-05 (Sunday 09/20)	PDT/UTC-07 (Saturday 09/19)	Speaker	Title of the talk	Affiliation
12:00 - 14:00	7:00 - 7:05	6:00 - 6:05	1:00 - 1:05	21:00 - 21:05	<b>Introduction to the workshop</b>		
12:05 - 12:20	7:05-7:20	6:05-6:20	1:05 - 1:20	21:05-21:20	Jack Weast	Global AV Standards Update and Remaining Challenges	Intel Corporation
12:20 - 12:35	7:20-7:35	6:20-6:35	1:20 - 1:35	21:20-21:35	Xuesong Wang	Calibration of Responsibility-Sensitive Safety Model on Vehicle-Bicycle Encounters Using Naturalistic Driving Study Data	Tongji University
12:35 - 12:50	7:35-7:50	6:35-6:50	1:35 - 1:50	21:35-21:50	Jeff Wishart	Driving Safety Performance Metrics for ADS-Equipped Vehicles	Arizona Institute of Automated Mobility
12:50 - 13:05	7:50-8:05	6:50-7:05	1:50 - 2:05	21:50-22:05	Yezhou Yang	Socially-Adept Autonomous Vehicles with Intent Inference and Motion Planning	ASU
13:05 - 13:20	8:05-8:20	7:05-7:20	2:05 - 2:20	22:05-22:20	Anthony Corso	Approaches for Black-Box Safety Validation	Stanford University
13:20 - 13:35	8:20-8:35	7:20-7:35	2:20 - 2:35	22:20-22:35	Chen Chai	Artificial Potential Field for Assessing and Improving Automated Driving Safety Performance at Complex Road Environments	Tongji University
13:35 14:00	8:35-9:00	7:35-8:00	2:35 - 3:00	22:35-23:00	<b>Q&amp;A and Panel Discussion</b>		

### WORKSHOP BLOCK 2

CST/UTC+08 (Sunday 09/20)	EEST/UTC+03 (Sunday 09/20)	CEST/UTC+02 (Sunday 09/20)	EST/UTC-05 (Sunday 09/20)	PDT/UTC-07 (Sunday 09/20)	Speaker	Title of the talk	Affiliation
21:00 - 21:05	16:00-16:05	15:00-15:05	9:00-9:05	6:00 - 6:05	<b>Introduction to the workshop</b>		
21:05 -21:20	16:05-16:20	15:05-15:20	9:05-9:20	6:05-6:20	Markus Maurer/Robert Graubohm	Towards Generic Safety Goals in the Concept Phase of AV	TU Braunschweig
21:20-21:35	16:20-16:35	15:20-15:35	9:20-9:35	6:20-6:35	Phil Koopman	Positive Trust Balance to Determine when to Deploy AVs	Edge Case Research
21:35-21:50	16:35-16:50	15:35-15:50	9:35-9:50	6:35-6:50	Matthias Althoff	Just-in-Time Verification of Autonomous Vehicles	TU Munich
21:50 - 22:05	16:50-17:05	15:50-16:05	9:50-10:05	6:50-7:05	Cornelius Buerkle	Towards a light-weight Application Level Monitor	Intel Corporation
22:05 - 22:20	17:05 - 17:20	16:05-16:20	10:05-10:20	7:05-7:20	Fabian Oboril	Risk-Aware Decision Making for Automated Vehicles	Intel Corporation
22:20 - 22:35	17:20-17:35	16:20-16:35	10:20-10:35	7:20-7:35	Jan Reich	SINADRA: Towards Situation-Aware Dynamic Risk Assessment of AV	Fraunhofer
22:35 - 22:50	17:35-17:50	16:35-16:50	10:35-10:50	7:35-7:50	Frederik Pasch	Handling of Unstructured Roads and Pedestrians in RSS	Intel Corporation
22:50 - 23:05	17:50-18:05	16:50-17:05	10:50-11:05	7:50-8:05	Christian Hubschneider	Towards Graph-Based Scenario Representation for Traffic Prediction	FZI
23:05 - 00:00	18:05-19:00	17:05-18:00	11:05-12:00	8:05-9:00	<b>Q&amp;A and Panel Discussion</b>		